



Development of a microwave land surface
emissivity algorithm for precipitation retrieval

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Microwave land surface emissivity

- ▶ **Microwave rainfall retrieval over land**
 - ▶ Remains challenging because the microwave surface emissivity is poorly constrained over land.
 - ▶ ϵ is highly variable over space and time, and depends on many factors including soil moisture, vegetation, snow cover, etc.
 - ▶ Relies on scattering signals from ice particles above rain.
 - ▶ Warm rain accompanied by little ice above is largely missed.
 - ▶ Dry, light snowfall is often left undetected.
- ▶ **Efforts to evaluate microwave land surface emissivity**
 - ▶ Model-based: Develop a land surface model and assign synthetic emissivity for each surface type etc.
 - ▶ **Observation-based: Retrieve emissivity from observed microwave T_b from scene to scene.**



Land sfc emissivity algorithm for GPM

- ▶ JAXA (domestic) GPM land emissivity algorithm
 - ▶ Team
 - ▶ H. Masunaga, F. A. Furuzawa, and H. Minda (Nagoya U).
 - ▶ Estimates ε from observed T_b s (Prigent et al., 2006).
 - ▶ **Utilizes radar observations for identifying rain-free scenes.**
 - ▶ A reliable measure to minimize rain contamination.
 - ▶ **An “EOF estimator” to derive high-frequency emissivities.**
 - ▶ To avoid noise from cloud emissions at high frequency T_b s.
 - ▶ A prototype algorithm is being experimented with
 - ▶ 1) TRMM TMI and PR for frequencies of 85 GHz and lower.
 - ▶ 2) AMSU collocated with PR for WV sounding channels (not shown today.)
 - ▶ Aimed at future implementation in the GSMaP algorithm.
 - ▶ ↔ NASA PMM ε algorithms for GPM radiometer/combined retrievals.



Retrieval methodology

Clear-sky emissivity algorithm (Prigent et al. 2006)

$$\tau(z_0, z_1) = \int_{z_0}^{z_1} \alpha(z) dz$$

$$T_{\text{atm}}^{\downarrow} = \int_H^0 T(z) [\alpha(z) / \mu] e^{-\tau(z,0)/\mu} dz + T_{\text{cosm}} e^{-\tau(0,H)/\mu}$$

$$T_{\text{atm}}^{\uparrow} = \int_0^H T(z) [\alpha(z) / \mu] e^{-\tau(z,H)/\mu} dz.$$

Atmospheric parameters (T , q_v , q_c) are estimated from JRA/JCDAS.

$$\varepsilon_p = \frac{Tb_p - T_{\text{atm}}^{\uparrow} - T_{\text{atm}}^{\downarrow} e^{-\tau(0,H)/\mu}}{e^{-\tau(0,H)/\mu} (T_{\text{surf}} - T_{\text{atm}}^{\downarrow})}$$

Emissivity is first estimated for rain-free scenes where TRMM PR sees no rain..



Emissivity for raining scenes

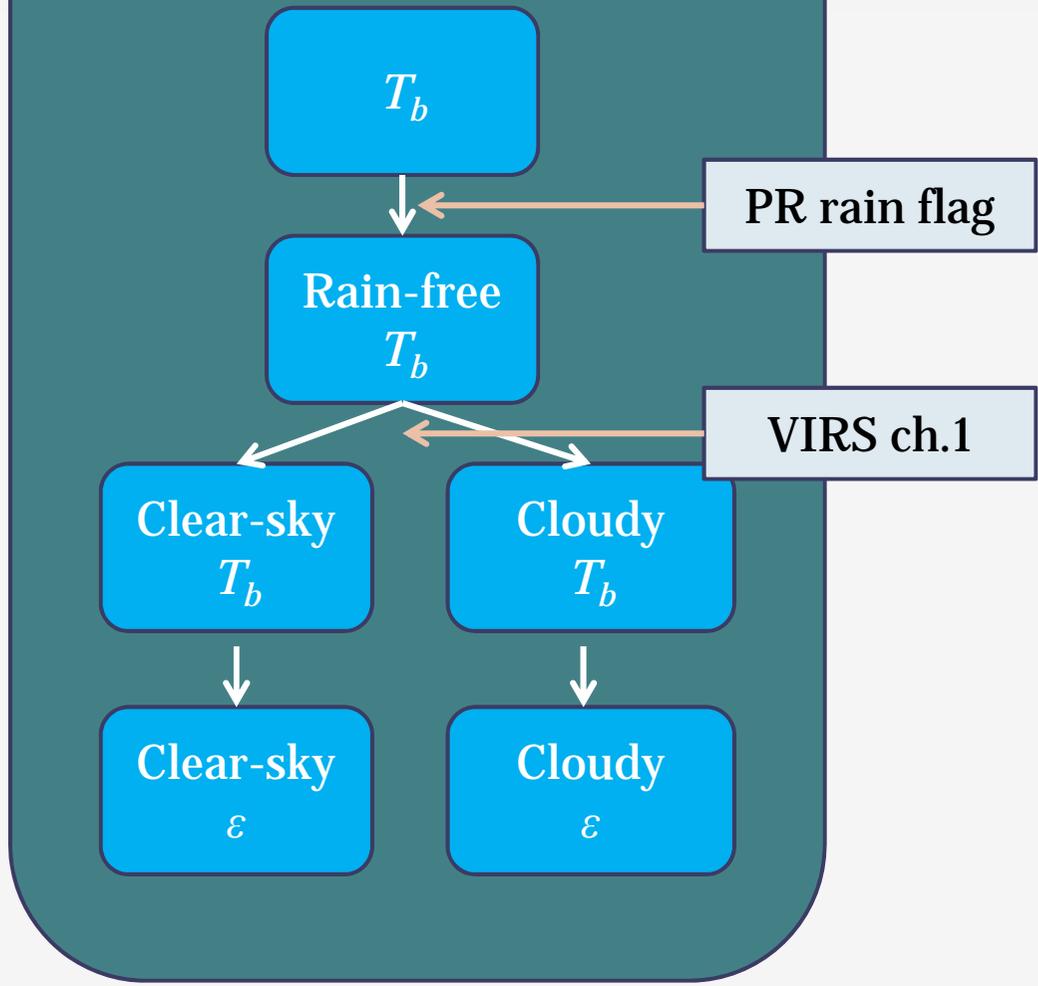
- Interpolate the clear-sky emissivity across raining scenes
 - Spatial averaging with Gaussian weights

$$\varepsilon_i = \frac{\sum_j \varepsilon_j \exp(-d_{ij}^2 / \sigma^2)}{\sum_j \exp(-d_{ij}^2 / \sigma^2)}$$

d_{ij} : distance between FOV_i and FOV_j
 σ : correlation length (= 0.1 deg)

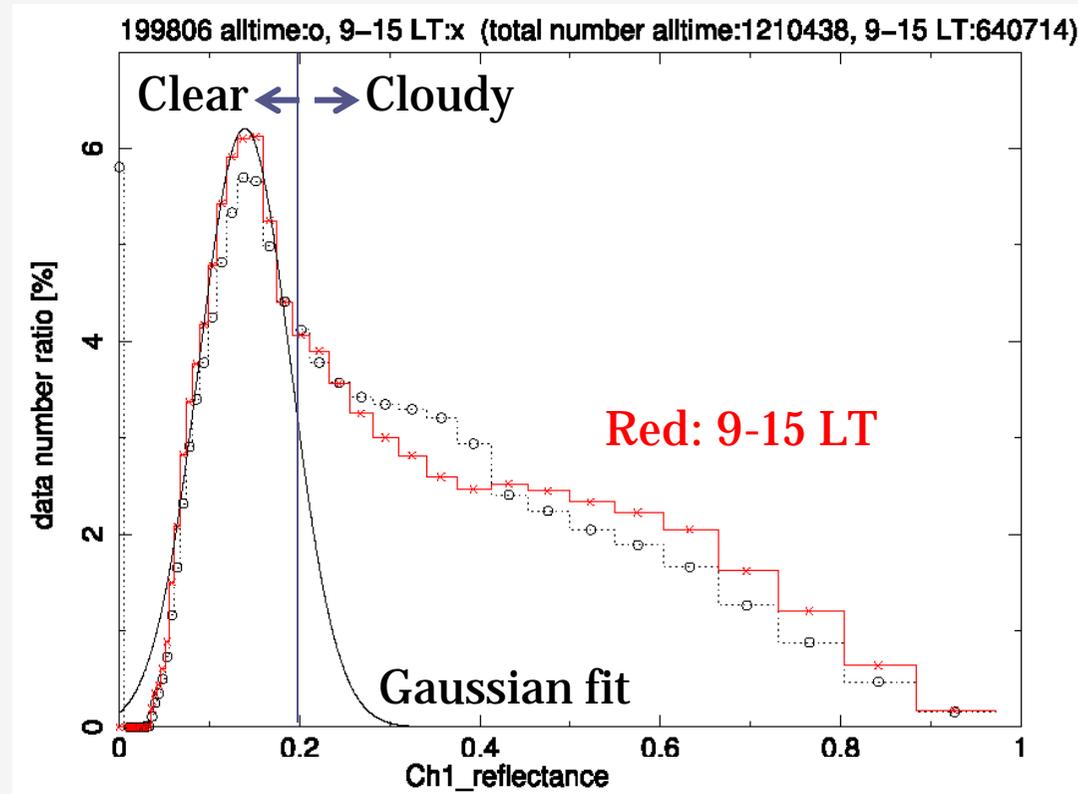


TMI ch. 1-4 (10, 19 GHz)

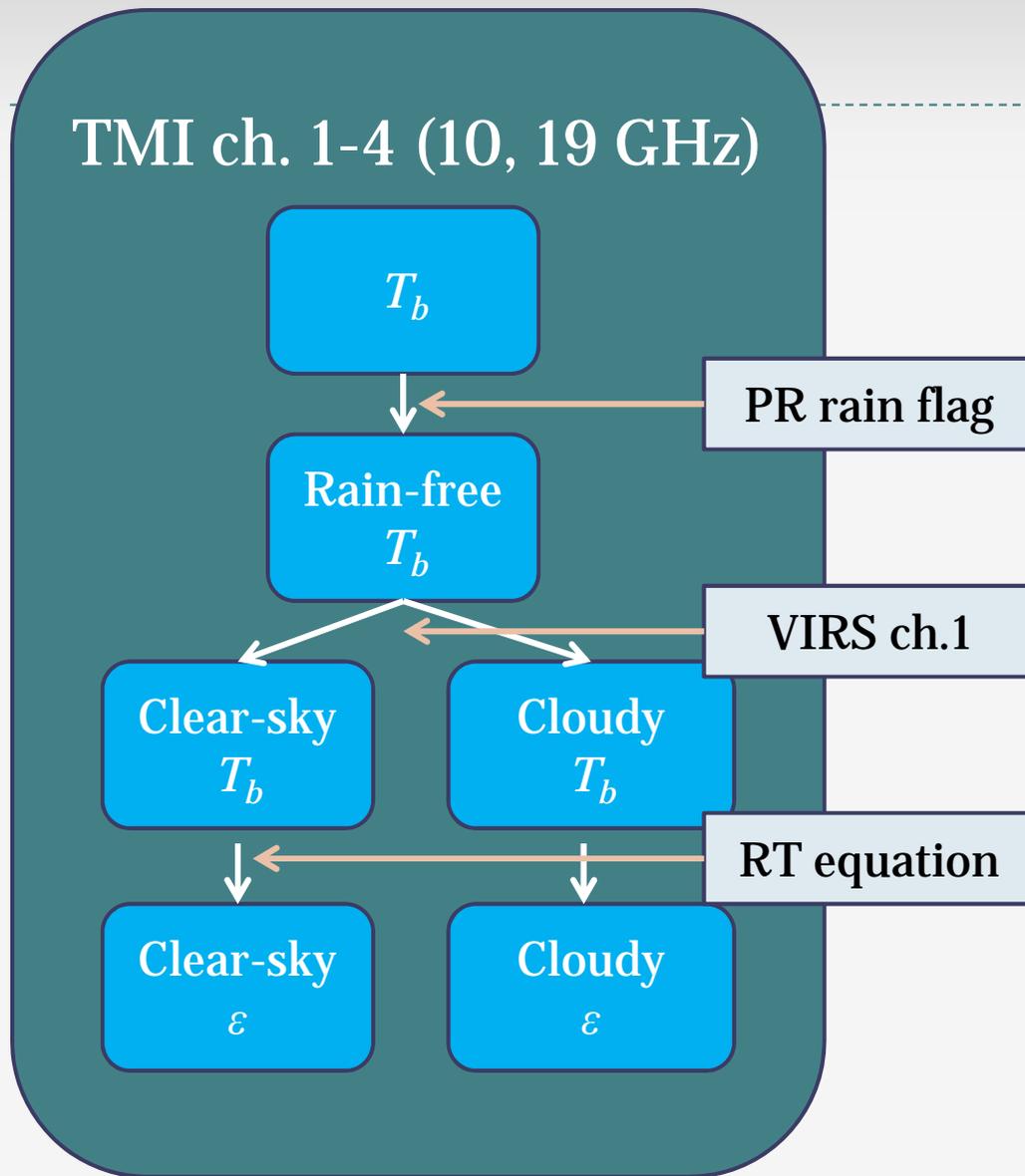


Cloud screening

- ▶ **VIRS-based cloud screening**
 - ▶ Cloud fraction < 0.22 within a $0.2^\circ \times 0.2^\circ$ box: clear sky
 - ▶ **Visible (ch.1) reflectance < 0.2** is defined as a cloud-free pixel.

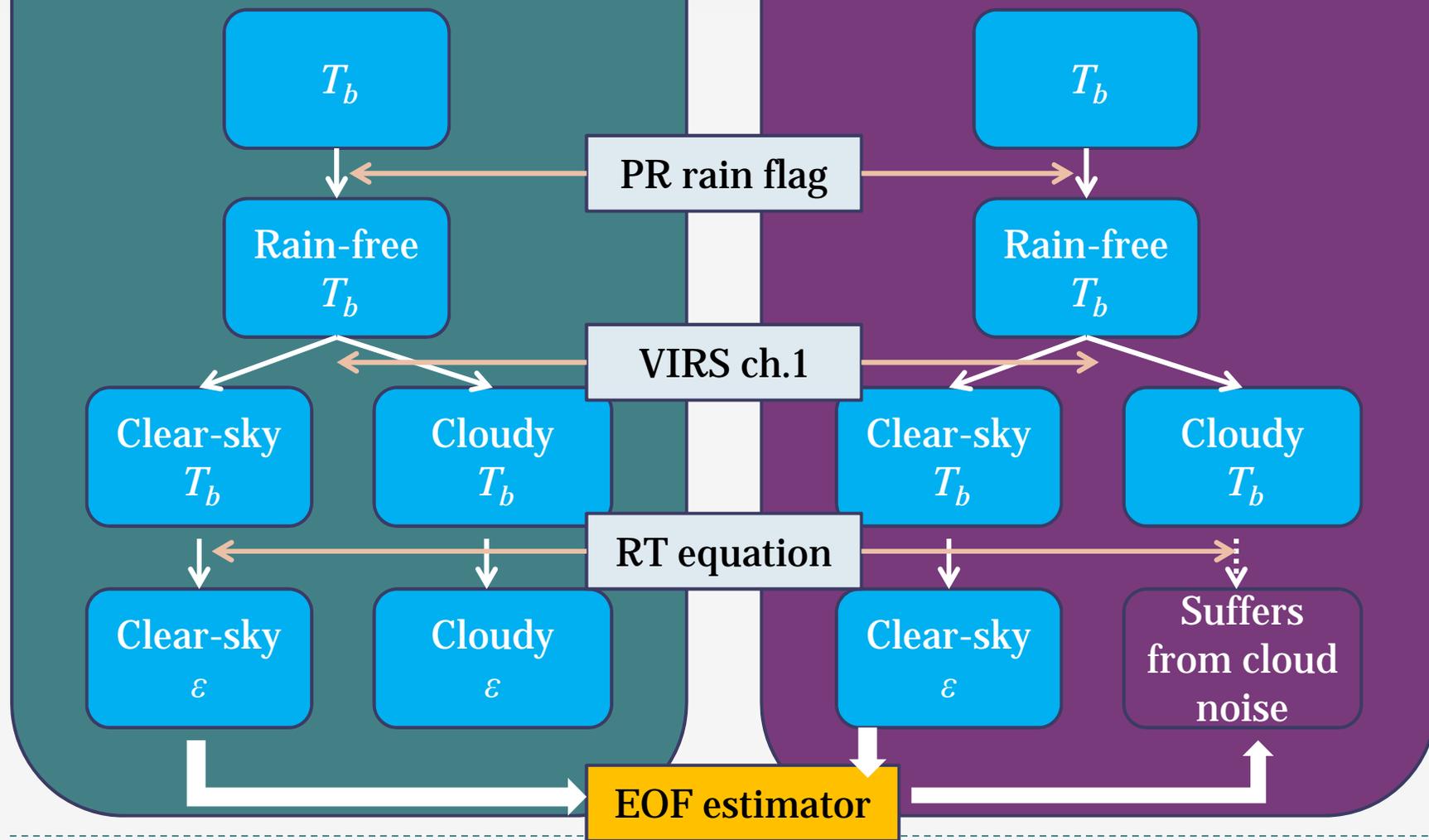


TMI ch. 1-4 (10, 19 GHz)



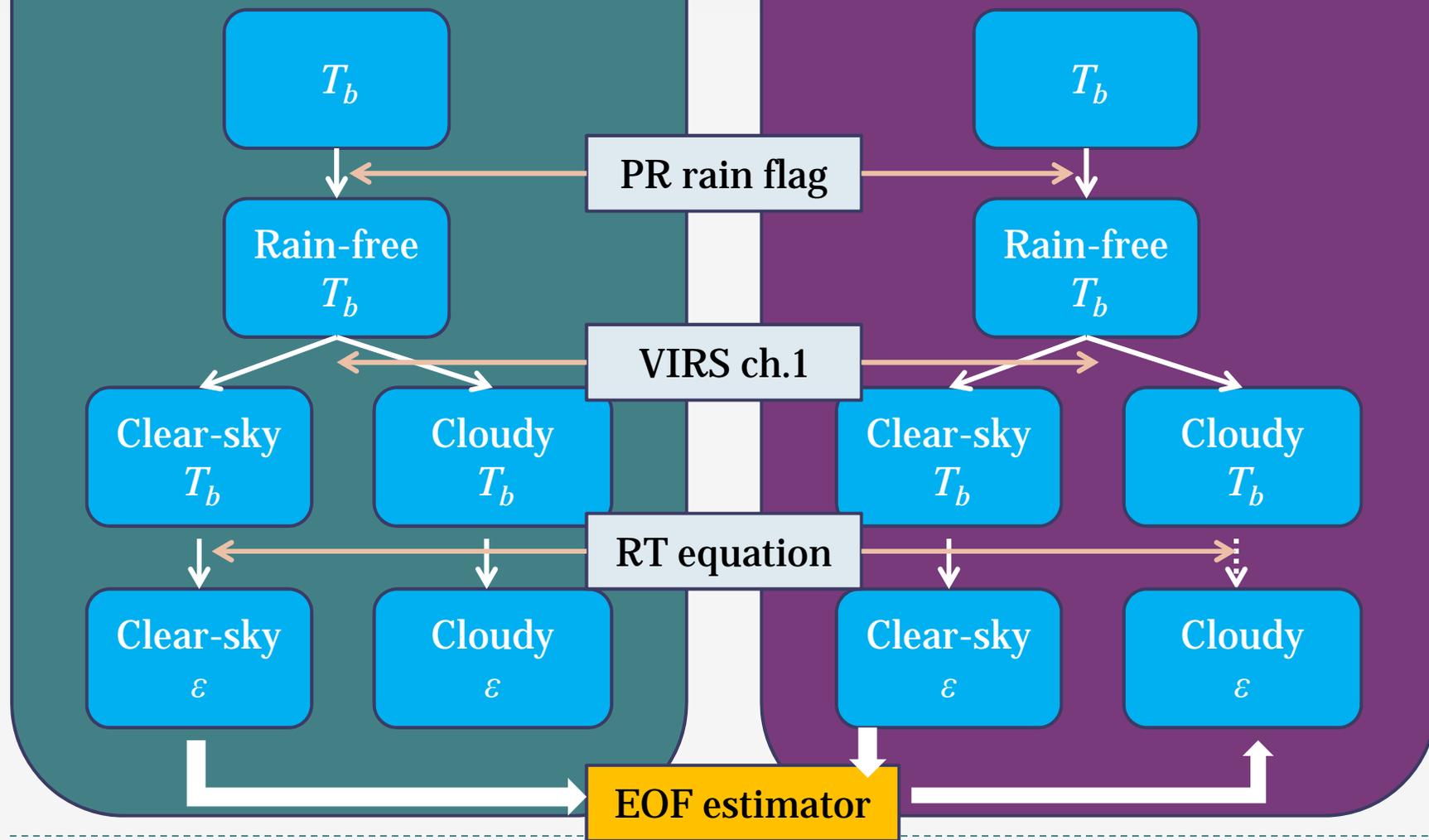
TMI ch. 1-4 (10, 19 GHz)

TMI ch. 5-9 (21-85 GHz)



TMI ch. 1-4 (10, 19 GHz)

TMI ch. 5-9 (21-85 GHz)



Recent algorithm updates

▶ Implementation of EOF-based estimator

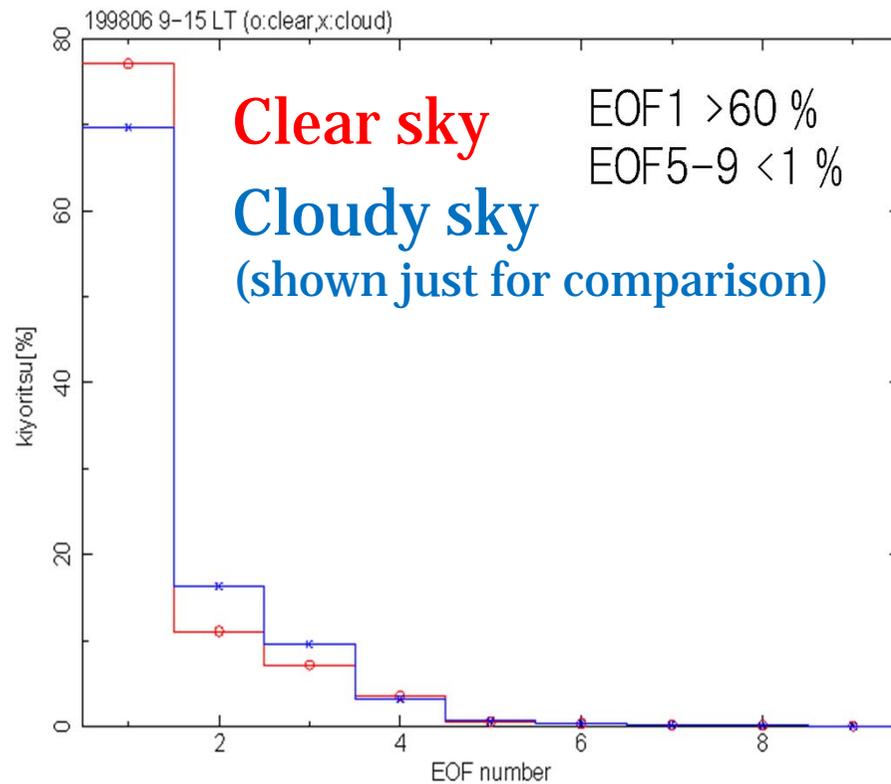
- ▶ ϵ at high frequencies (> 85 GHz) suffers from the water vapor and cloud water uncertainties.
- ▶ This problem may be avoided by an “EOF estimator”:
 - ▶ 1) Retrieve ϵ at each frequency for **cloud-free** scenes.
 - ▶ 2) Compute EOF s of the clear-sky ϵ across all 9 TMI frequencies.
 - These EOFs represent the inter-frequency covariance of ϵ .
 - ▶ 3) All-sky (clear- and cloudy-sky w/o rain) retrieval is run with the 4 low-frequency channels (10 GHz V/H and 19 GHz V/H).
 - These low frequencies are likely insensitive to non-raining clouds.
 - ▶ 4) ϵ at higher frequencies (21, 37, and 85 GHz) are obtained by extrapolating the lower 4 channels exploiting the first 4 EOFs.
 - The first 4 EOFs are assumed to explain most of the variability in ϵ .



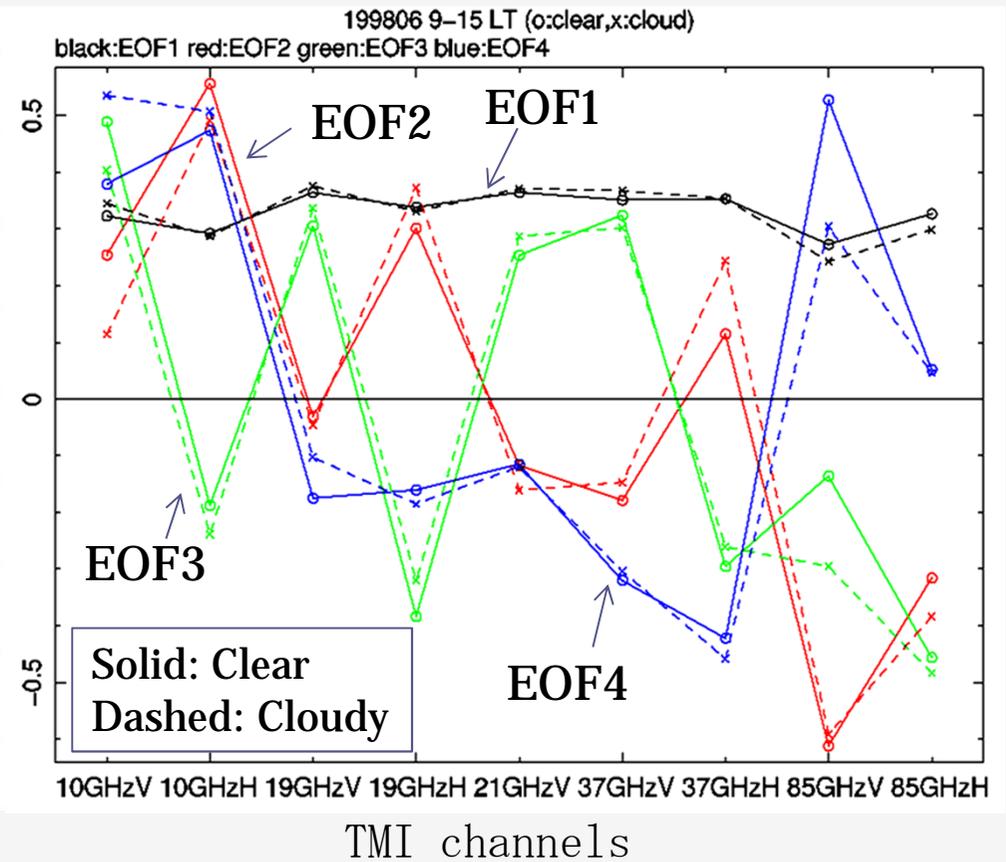
EOF properties

1998 (Jun) 9-15LT

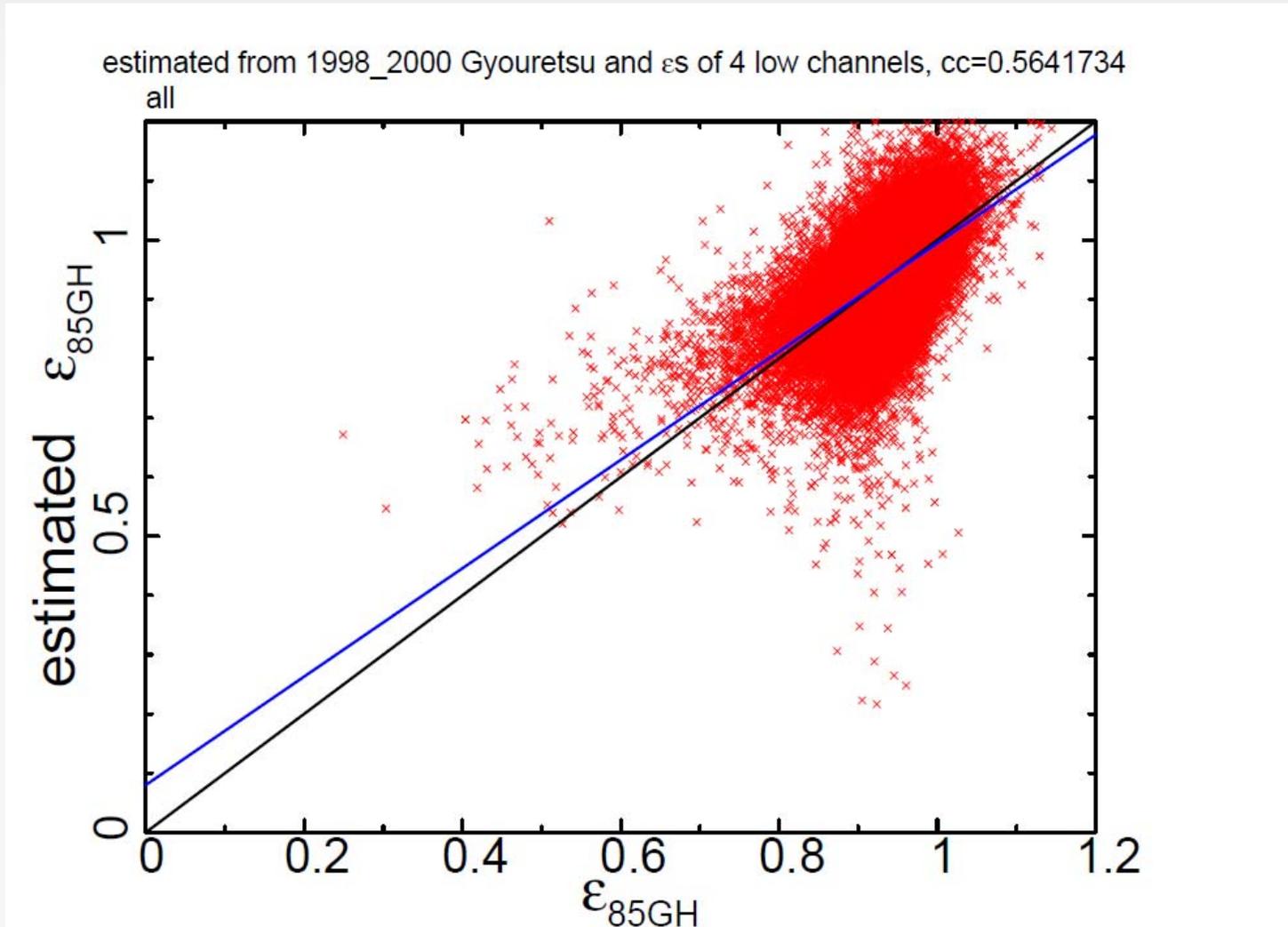
Contribution to total variability



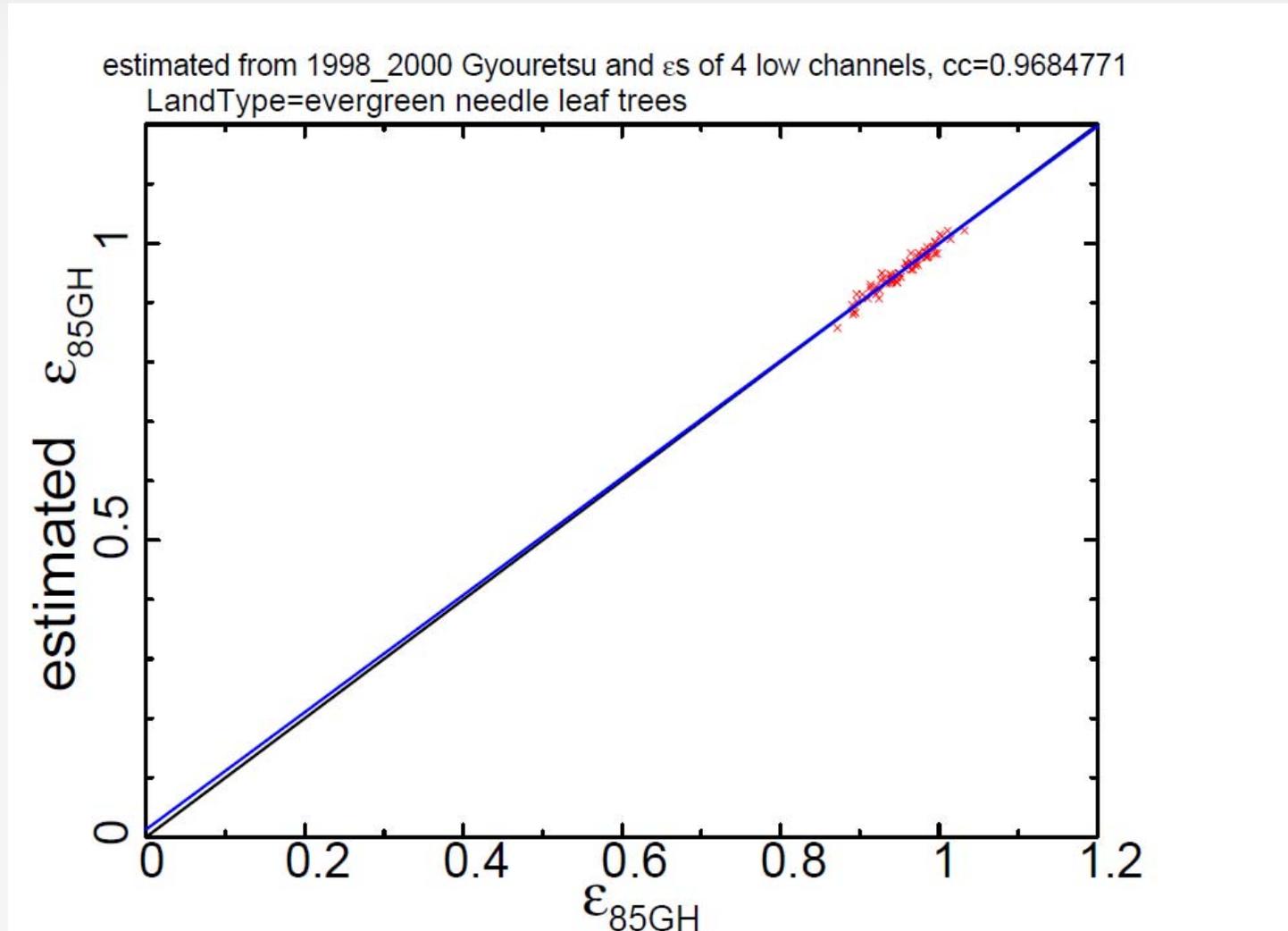
EOF components



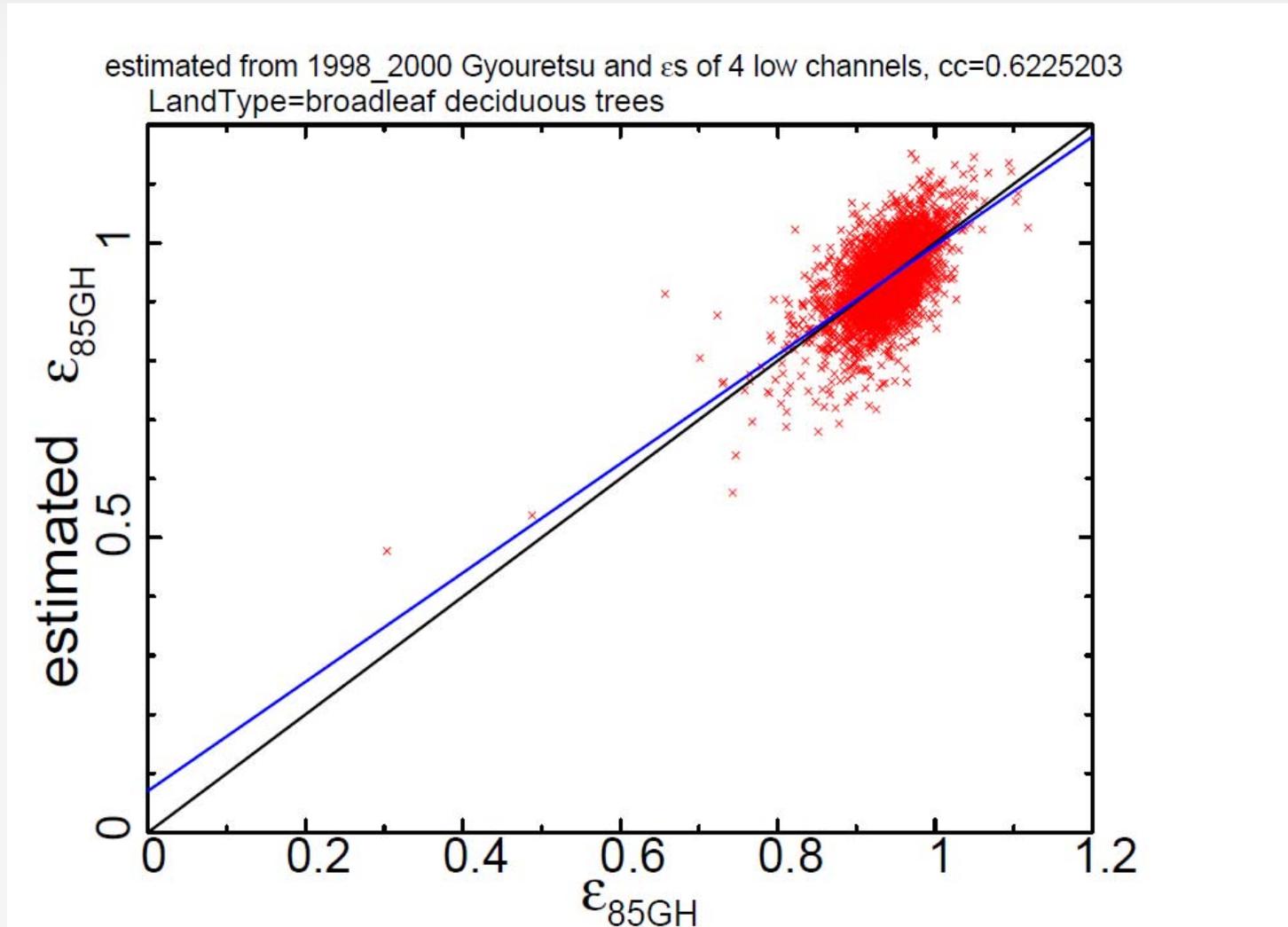
Clear-sky 85 GHz ϵ w or w/o EOF estimator



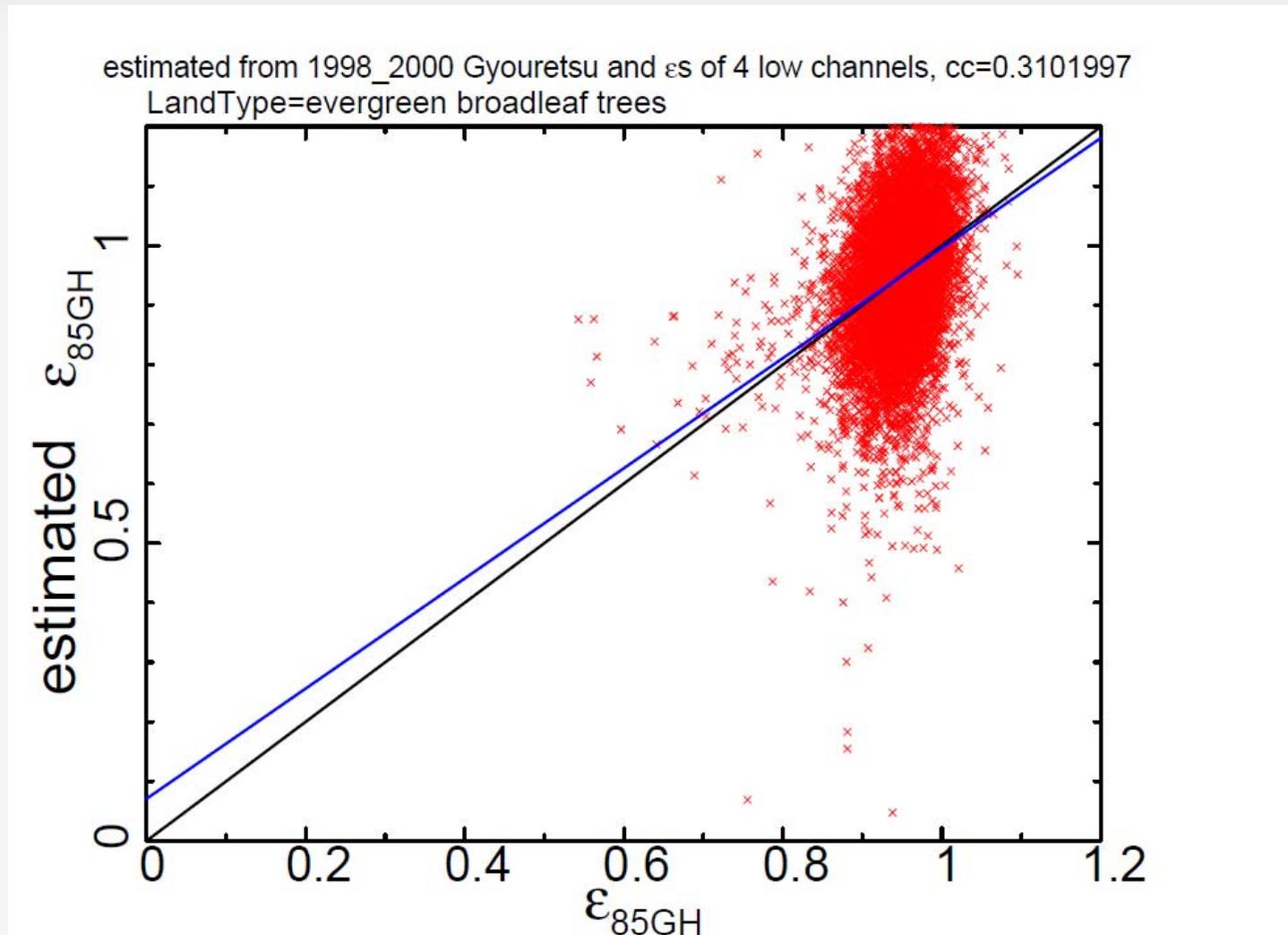
Land-type breakdown -1: evergreen needle leaf



Land-type breakdown -2: broadleaf deciduous

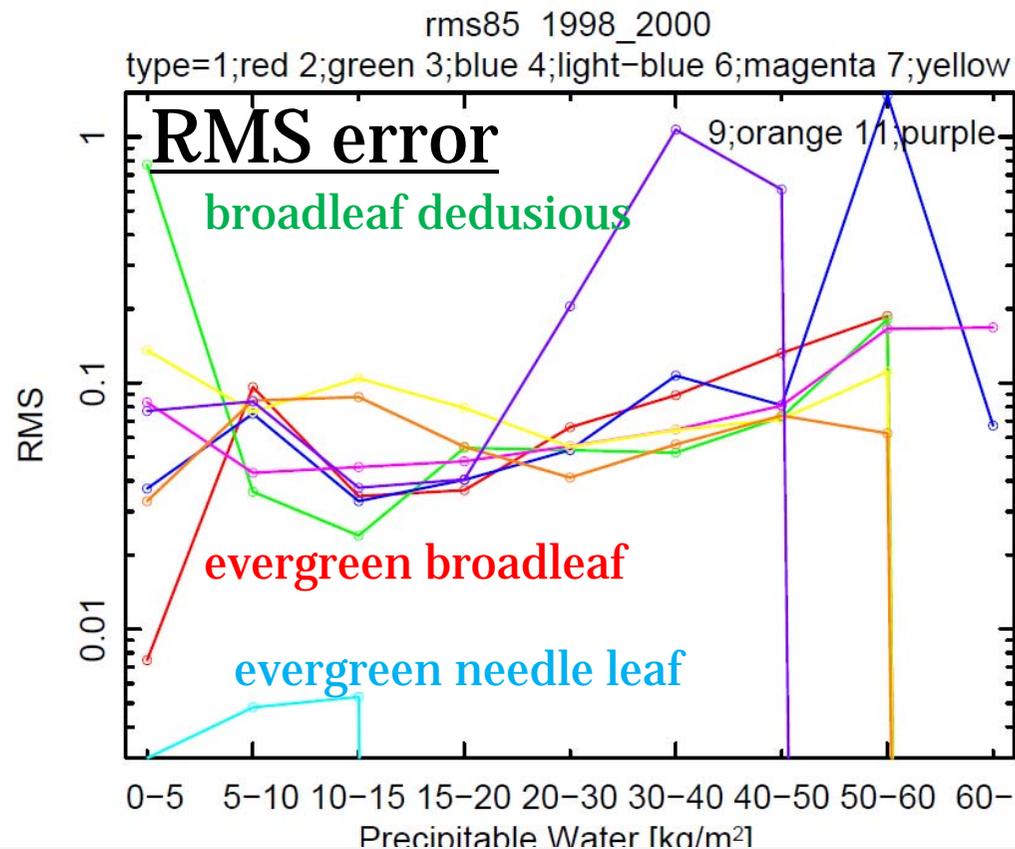


Land-type breakdown -3: evergreen broadleaf



What degrades the EOF performance?

- ▶ Possible causes for the poor performance
 - ▶ Water vapor uncertainty?

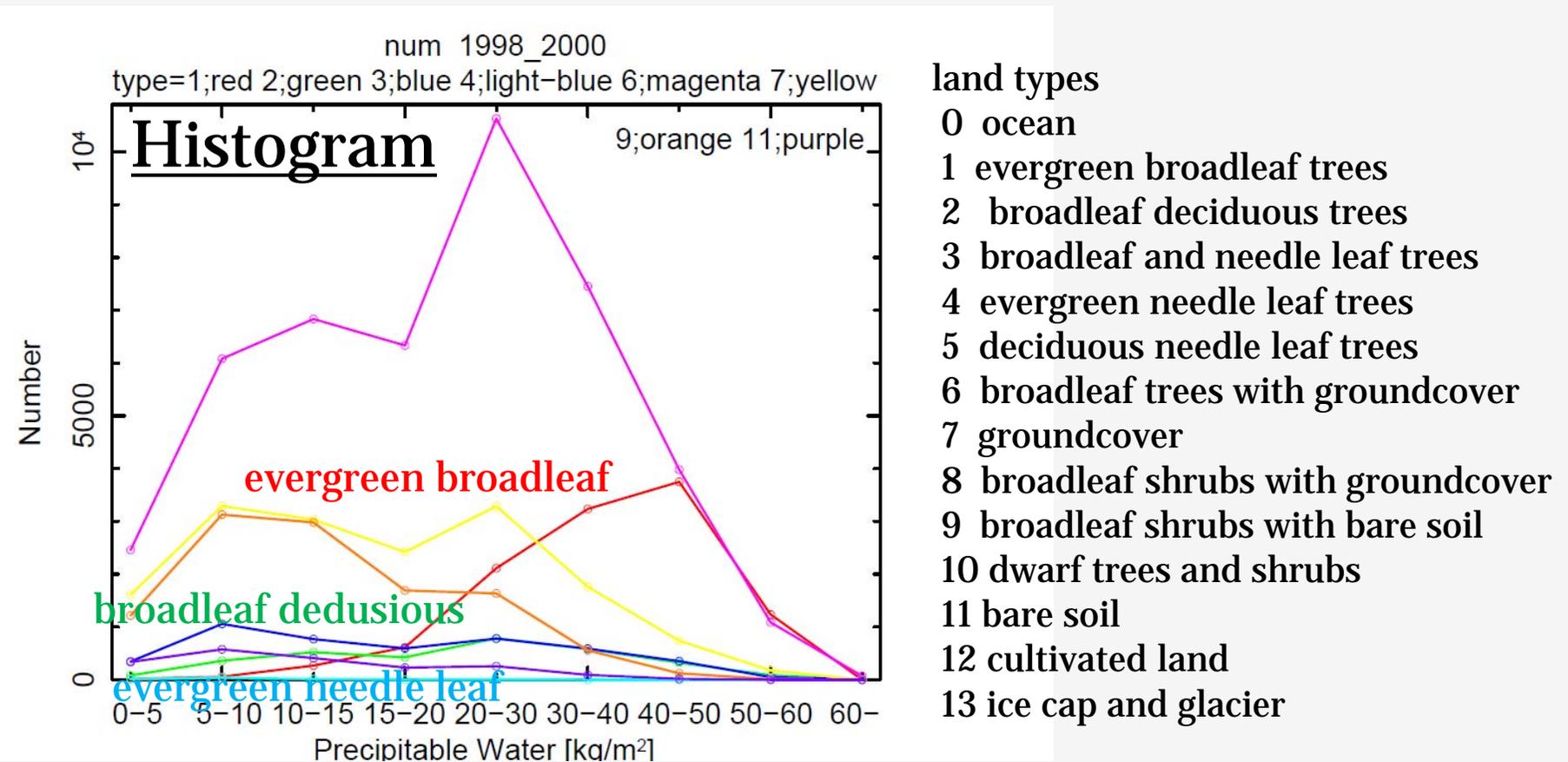


land types

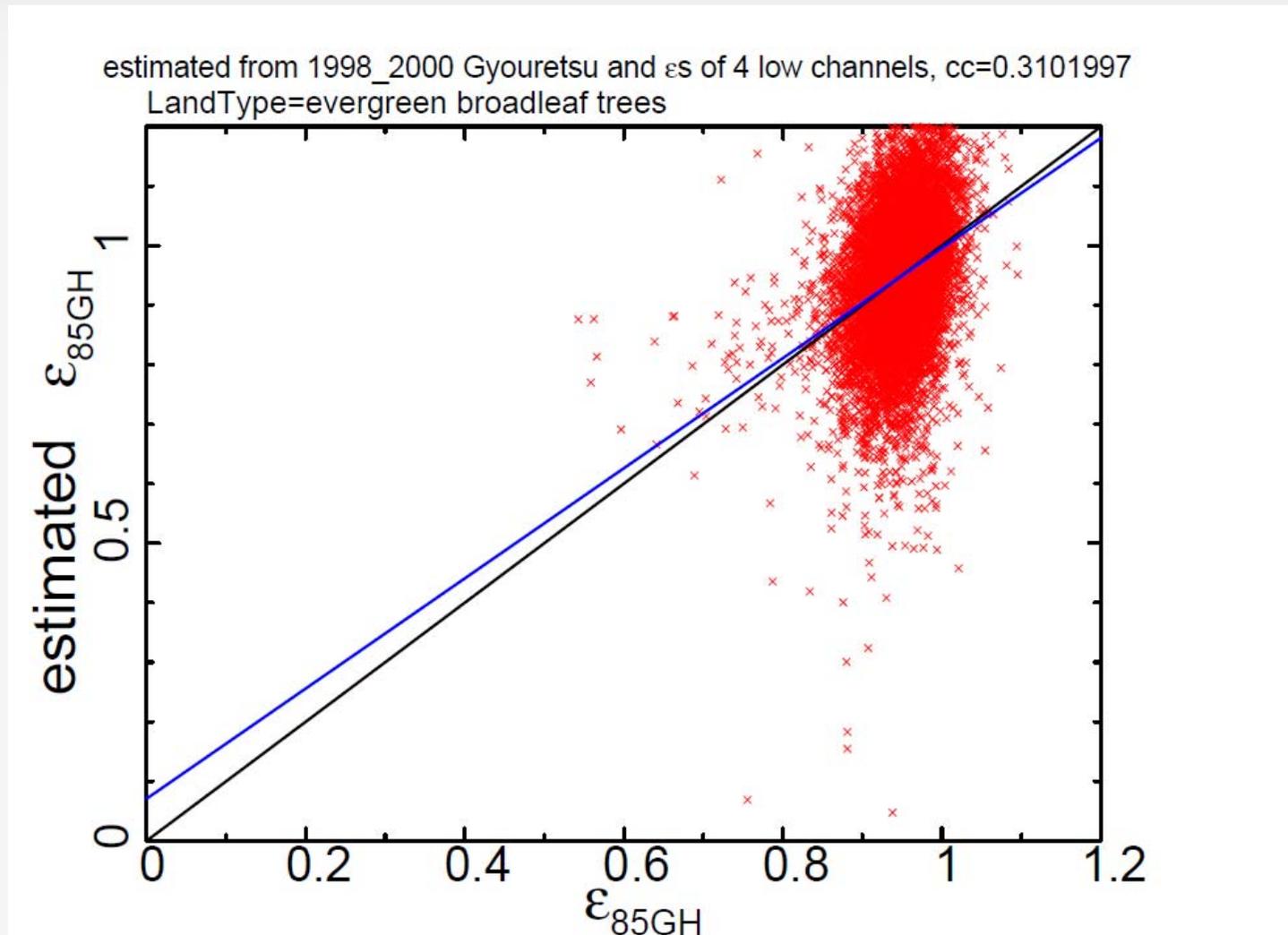
- 0 ocean
- 1 evergreen broadleaf trees
- 2 broadleaf deciduous trees
- 3 broadleaf and needle leaf trees
- 4 evergreen needle leaf trees
- 5 deciduous needle leaf trees
- 6 broadleaf trees with groundcover
- 7 groundcover
- 8 broadleaf shrubs with groundcover
- 9 broadleaf shrubs with bare soil
- 10 dwarf trees and shrubs
- 11 bare soil
- 12 cultivated land
- 13 ice cap and glacier

What degrades the EOF performance?

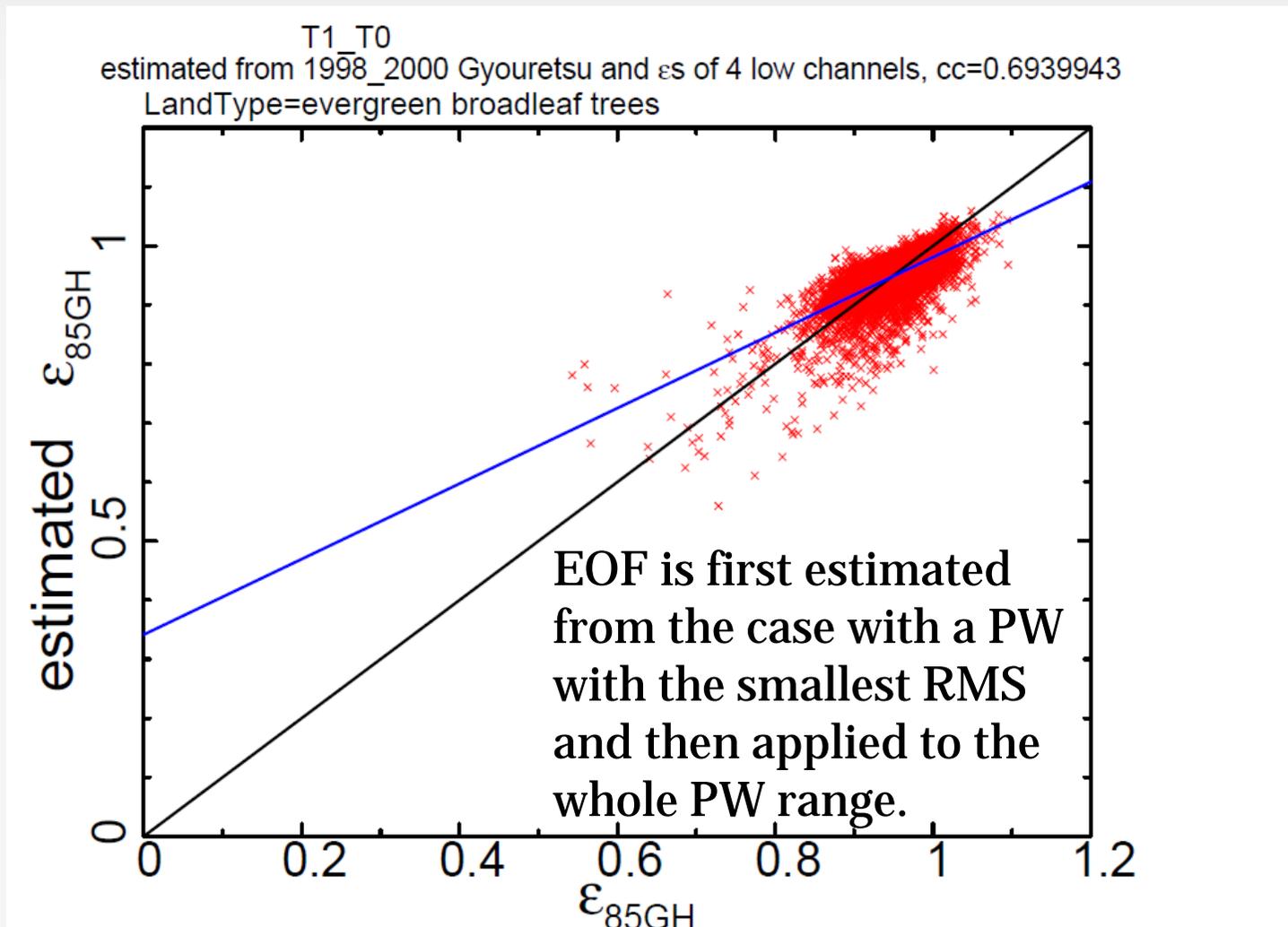
- ▶ Possible causes for the poor performance
 - ▶ Water vapor uncertainty, combined with sampling error?



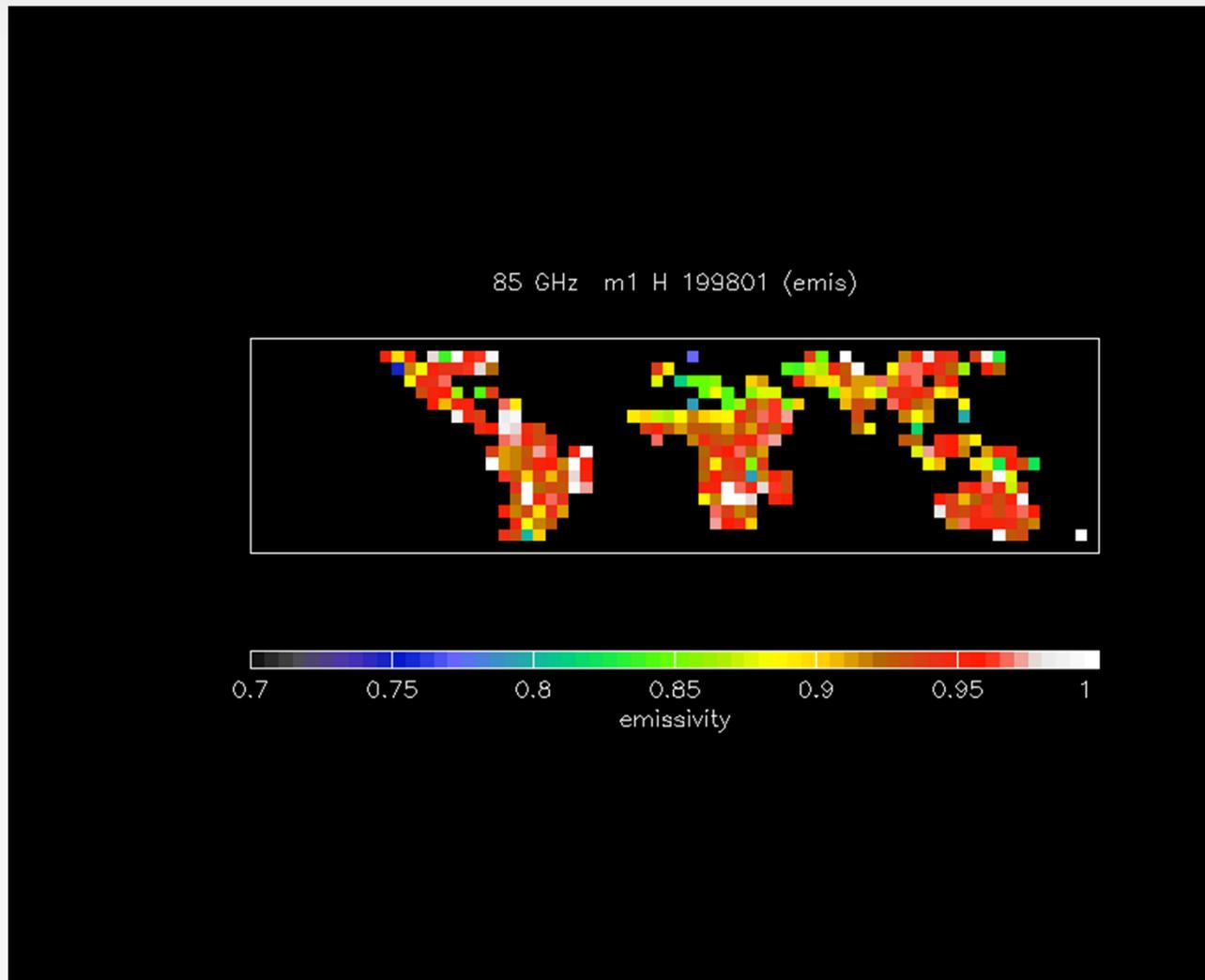
Land-type breakdown -3: evergreen broadleaf



Using the EOF from the best case scenario



Global map: monthly 85 GHz H emissivity



Summary and future tasks

- ▶ **Land surface emissivity algorithm**
 - ▶ A before-launch algorithm is being tested with TRMM.
 - ▶ Simultaneous radar obs. provides a reliable rain screening.
 - ▶ Cloud contamination is mitigated by an EOF estimator.
 - ▶ Performance is generally improved when the EOF estimator is applied to different land surface types individually (with exceptions).
 - ▶ Will continue to work for the further refinement of the algorithm.
- ▶ **Collaboration plans**
 - ▶ Will retain the close collaboration with the GSMP team.
 - ▶ Also will continue to participate in the emissivity inter-comparison project by NASA LSWG.
 - ▶ Ferraro et al. (IEEE TGRS, 2012), Tian et al. (IEEE TGRS, 2014), Norouzi et al., (AGU fall meeting, 2013), etc.

